


Sylvain Calinon, Paul Evrard, Elena Gribovskaya, Aude Billard, and Abderrahmane Kheddar. Learning collaborative manipulation tasks by demonstration using a haptic interface. In *ICAR: International Conference on Advanced Robotics*, pages 1–6, Munich, Germany, June 2009. URL [https://hal-lirmm.ccsd.cnrs.fr/lirmm-00798700](https://hal-lirmm.ccsd.cnrs.fr/lirmm-00798700)