


Pierre Biasutti, Jean-François Aujol, Mathieu Brédif, and Aurélie Bugeau. DISOCCLUSION OF 3D LIDAR POINT CLOUDS USING RANGE IMAGES. In *ISPRS International Society for Photogrammetry and Remote Sensing (CMRT)*, Hannover, Germany, June 2017a. URL https://hal.archives-ouvertes.fr/hal-01522366


P Biasutti, Jean-François Aujol, Mathieu Brédif, and Aurélie Bugeau. Anisotropic diffusion and inpainting of orthophotographs from mobile LiDAR. In 20ème Congrès national sur la Reconnaissance des Formes et l’Intelligence Artificielle (RFIA 2016), Clermont-Ferrand, France, June 2016. URL https://hal.archives-ouvertes.fr/hal-01316487

M Brédif, B Vallet, Andrés Serna, Beatriz Marcotegui, and N Paparoditis. TERRAMOBILITA/IQMULUS URBAN POINT CLOUD CLASSIFICATION BENCHMARK. In Workshop on Processing Large Geospatial Data, Cardiff, United Kingdom, July 2014. URL https://hal.archives-ouvertes.fr/hal-01101621.


Florent Lafarge, Renaud Keriven, and Mathieu Brédif. Combining meshes and geometric primitives for accurate and semantic modeling. In British Machine Vision Conference (BMVC), London, United Kingdom, September 2009a. URL https://hal.inria.fr/hal-00781776.

Florent Lafarge, Renaud Keriven, and Mathieu Brédif. Combining meshes and geometric primitives for accurate and semantic modeling. In BMVC, pages 38.1–38.11, Londres, United Kingdom, September 2009b. URL https://hal-enpc.archives-ouvertes.fr/hal-00834944.


Pierre Biasutti, Jean-François Aujol, Mathieu Brédif, and Aurélie Bugeau. Diffusion and inpainting of reflectance and height LiDAR orthoimages. working paper or preprint, October 2017b. URL https://hal.archives-ouvertes.fr/hal-01322822.

Marco Bevilacqua, Jean-François Aujol, Mathieu Brédif, and Aurélie Bugeau. Joint Inpainting of Depth and Reflectance with Visibility Estimation. working paper or preprint, July 2016b. URL https://hal.archives-ouvertes.fr/hal-01348304.